TOSHIBA MACHINE

NEW PRODUCT



- Low cost Excellent performance at affordable prices.
- Improved weight capacity and allwable inertia Expanded applicability of multi-hand with improved weight capacity and allowable inertia.
- Energy-efficient

Up to 20% reduction in required power-supply capacity compared with our previous models. Low-power consumption robots ideal for energy conservation era.





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Model		THL400	
Туре		Horizontal multi-joint	
No. of controlled axes		4	
Arm length		400mm (225mm+175mm)	
Working	Axis 1	±125°	
enve l ope	Axis 2	±145°	
	Axis 3 (Z-axis)	0~160mm	
	Axis 4 (Z-axis rotation)	±360°	
Maximum *1	Axis 1	660°/s	
speed	Axis 2	660°/s	
	Axis 3 (Z-axis)	1120mm/s	
	Axis 4 (Z-axis rotation)	1500°/s	
	Composite	6,3m/s	
Cycle time (v	with 2kg load) *2	0.47s	
Maximum payload mass		5kg	
Allowable moment of inertia		0₌05kg · m²	
Positioning*3	X—Y	±0.01mm	
repeatability	Z (Axis 3)	±0.015mm	
	Axis θ (Z-axis rotation)	±0.007°	
Hand wiring		8 inputs/8 outputs	
Hand pneumatic joints *4		φ4 ×3 pcs	
Position detection		Absolute	
Robot controller cable		3,5m	
Power capacity		0.7kVA	
Mass		13kg	

- *1 : Acceleration/deceleration rates may be limited according to the motion pattern, load mass and amount of offset.

 *2 : When the environment temperature is constant 20°C. Positioning repeatable accuracy in one-direction movement. Not absolute positioning accuracy.

 *3 : Horizontal 300mm, vertical 25mm, round-trip. Continous operation is not possible beyond the effective load ratio.

- *4 : Pneumatic joints are provided on the base. Please refer to the drawings for the

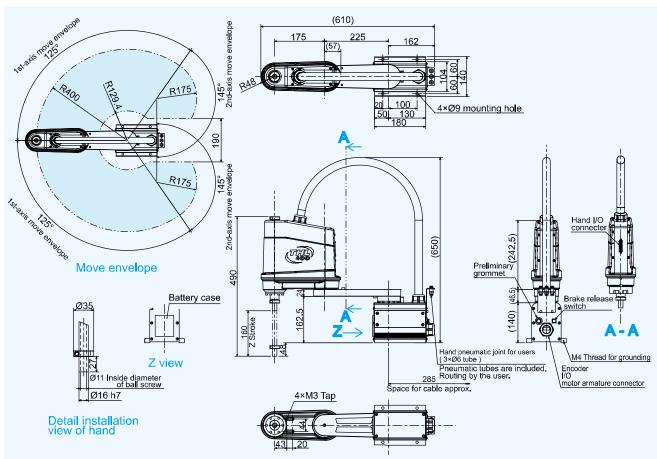
Controller **Specifications**



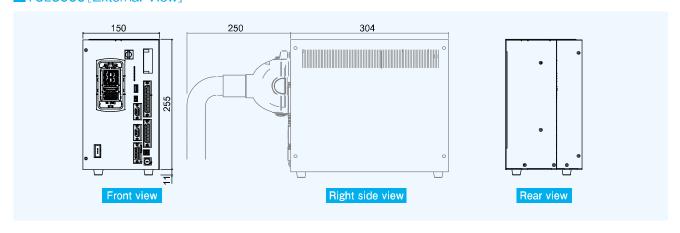
details of the pneumatic joints. Pipes to be are provided by the customers.		
	Model	TSL3000
	No. of controlled axes	4 axes
	Motion modes	PTP, CP(Continuous Path ; Linear, Circular),
		Short-Cut, Arch Motion
	Storage capacity	Approx. Total: 6400 point + 12800 steps
		1 program : 2000 point + 3000 steps
	No. of registrable programs	Maximum 256
	Programming language	SCOL(similar to BASIC)
	Teaching unit	Teach pendant TP1000
	(Option)	(Cable length 5m, 3-point enable switch)
	External I/O signals	8 inputs / 8 outputs(Plus or minus common selectable)
	Hand control signals	8 inputs / 8 outputs
	External operation	Input : cycle operation mode, start, stop. (13 signals)
	signal	output : Servo ON, emergency stop, etc. (10 signals)
	Serial communication ports	RS232C : 2 ports
	Other functions	Torque control,Interruptive functions, self-diagnosis,
		I/O control and communications during motion,
		Coordinate calculations, Built-in PLC, etc.
	Power supply	Single phase AC190V~250V , 50/60Hz(±1Hz)
	Outer Dimensions and Mass	150(W)×256(H)×304(D)[mm] , 6₌5kg
	PC Software for Programming	TSPC : Program editor, teaching,
	Support(Option)	remote operation, etc.
١.	Option	I/O extension, Field-network
		(CC-Link,Devive-Net,Profibus)*5

*5:CC-Link is a registered trademark of CC-Link Partner Association. DeviceNet is registered trademark of ODVA. Profibus is a registered trademark of Profibus User Organization.

THL400[External View]



TSL3000 [External View]



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Before operating the industrial robot, read through and completely understand the instruction manuals.

■The contents included in this catalog are subject to change without prior notice to reflect improvements.